

1 I CLAIM:

2 1. A method for manufacturing an object having a potential {x} that is
3 generated in response to a field {f} applied thereto, the method comprising the steps of:
4 generating a computerized mathematical model of the object by discretizing a
5 geometric model of the object into a plurality of finite elements and specifying values for
6 the field {f} and potential {x} relative to the finite elements;
7 specifying that the material properties of the finite elements have a particular
8 symmetry;
9 calculating a material property matrix [k] based on the relationship $\{f\}=[k]\{x\}$
10 and the specified symmetry;
11 extracting material property coefficients from the material property matrix [k] for
12 each finite element in the computerized mathematical model;
13 comparing the extracted material property coefficients to material property
14 coefficients for known materials to match the extracted material property coefficients to
15 the material property coefficients for known materials;
16 determining manufacturing parameters for controlling manufacturing equipment
17 based on the matched material property coefficients; and
18 controlling the manufacturing equipment in accordance with the determined
19 manufacturing parameters to thereby manufacture the object.

1 2. The method according to claim 1, wherein the material properties of the
2 finite elements are specified to be isotropic.

1 3. The method according to claim 1, wherein the material properties of the
2 finite elements are specified to be transversely isotropic.

1 4. The method according to claim 1, wherein the step of generating a
2 computerized mathematical model of the object further includes determining the smallest
3 volume increment that can be manufactured using the composite manufacturing
4 equipment.

1 5. The method according to claim 1, wherein the field {f} is a mechanical
2 force field and the potential {x} is a displacement.

1 6. The method according to claim 1, wherein the field {f} is an electric
2 current field and the potential {x} is a voltage.

1 7. The method according to claim 1, wherein the field {f} is a magnetic field
2 and the potential {x} is a magnetic vector potential.

1 8. The method according to claim 1, wherein the field {f} is a thermal flux
2 field and the potential {x} is a temperature.

1 9. The method according to claim 1, wherein the field {f} is a fluid velocity
2 field and the potential {x} is a fluid potential.

1 10. The method according to claim 1, wherein the step of controlling the
2 manufacturing equipment comprises controlling a composite manufacturing equipment
3 for manufacturing a composite material.

1 11. The method according to claim 10, wherein the composite material
2 comprises structural fibers laminated in a matrix.

1 12. The method according to claim 11, wherein the matrix includes biologic
2 material.

1 13. The method according to claim 11, wherein the matrix includes bone.

- 1 14. The method according to claim 11, wherein the matrix includes crushed
2 bone.
- 1 15. The method according to claim 11, wherein the matrix includes co-factors.
- 1 16. The method according to claim 11, wherein the matrix includes biological
2 cells.
- 1 17. The method according to claim 11, wherein the matrix includes bio-active
2 materials.
- 1 18. The method according to claim 11, wherein the matrix includes
2 medications.
- 1 19. The method according to claim 11, wherein the matrix includes
2 antibiotics.
- 1 20. The method according to claim 11, wherein the matrix includes
2 radioactive materials.
- 1 21. The method according to claim 1, wherein the object being manufactured
2 is a prosthetic implant for replacing a body part and the force {f} and displacement {x}
3 are specified based on the in vivo forces applied to the body part to be replaced and the in
4 vivo displacements generated in the body part to be replaced when the forces are applied
5 thereto.
- 1 22. An article of manufacture made in accordance with the method of claim 1,
2 wherein the article is selected from the group consisting of an automobile part, an aircraft
3 part, a prosthetic implant, a golf club shaft, a tennis racket, a bicycle frame, and a fishing
4 pole, and wherein different portions of the article have different material properties

5 corresponding to the matched extracted material property coefficients for known
6 materials.

1 23. A prosthetic implant manufactured in accordance with the method of
2 claim 1.

1 24. A golf club manufactured in accordance with the method of claim 1.

1 25. A computer-implemented method for determining machine control
2 instructions for manufacturing an object having a potential {x} that is generated in
3 response to a field {f} applied thereto, the method comprising the steps of:
4 generating a computerized mathematical model of the object by discretizing a
5 geometric model of the object into a plurality of finite elements and specifying values of
6 the field {f} and potential {x} relative to the finite elements;
7 specifying that the material properties of the finite elements have a particular
8 symmetry;
9 calculating a material property matrix [k] based on the relationship $\{f\}=[k]\{x\}$
10 and the specified symmetry;
11 extracting material property coefficients from the material property matrix [k] for
12 each finite element in the computerized mathematical model;
13 comparing the extracted material property coefficients to material property
14 coefficients for known materials to match the extracted material property coefficients to
15 the material property coefficients for known materials;
16 determining manufacturing parameters for controlling manufacturing equipment
17 based on the matched material property coefficients; and

18 generating machine control instructions for controlling the manufacturing
19 equipment in accordance with the manufacturing parameters.

1 26. The method according to claim 25, wherein the object being manufactured
2 is a prosthetic implant for replacing a body part and the force {f} and displacement {x}
3 are specified based on the in vivo forces applied to the body part to be replaced and the in
4 vivo displacements generated in the body part to be replaced when the forces are applied
5 thereto.

1 27. The method according to claim 25, wherein the step of generating machine
2 control instructions comprises generating machine control instructions for controlling
3 composite manufacturing equipment for manufacturing a composite material.

1 28. The method according to claim 27, wherein the composite material
2 comprises structural fibers laminated in a matrix.

1 29. The method according to claim 28, wherein the matrix includes biologic
2 material.

1 30. The method according to claim 28, wherein the matrix includes bone.

1 31. The method according to claim 28, wherein the matrix includes crushed
2 bone.

1 32. The method according to claim 28, wherein the matrix includes co-factors.

1 33. The method according to claim 28, wherein the matrix includes biological
2 cells.

1 34. The method according to claim 28, wherein the matrix includes bio-active
2 materials.

1 35. The method according to claim 28, wherein the matrix includes
2 medications.

1 36. The method according to claim 28, wherein the matrix includes
2 antibiotics.

1 37. The method according to claim 28, wherein the matrix includes
2 radioactive materials.

1 38. A computer system programmed to perform the method of claim 25.

1 39. A control system programmed with machine control instructions for
2 controlling composite manufacturing equipment to manufacture a composite object,
3 wherein the machine control instructions are generated in accordance with the method of
4 claim 25.

1 40. Composite manufacturing equipment comprising a control system
2 programmed with machine control instructions for controlling the composite
3 manufacturing equipment to manufacture a composite object, wherein the machine
4 control instructions are generated in accordance with the method of claim 25.

1 41. A method for manufacturing an object for which a defined field {f}
2 generates a potential {x} in response thereto, the method comprising the steps of:

3 (1) generating a computerized mathematical model of the object by
4 discretizing a geometric model of the object into a plurality of finite elements;

5 (2) specifying values of the field {f} and the potential {x} relative to the finite
6 elements;

7 (3) specifying that the material properties of the finite elements have a
8 particular symmetry;

9 (4) calculating a material property matrix $[k]$ based on the relationship
10 $\{f\}=[k]\{x\}$ and the specified symmetry, wherein the material property matrix $[k]$
11 comprises a plurality of values each corresponding to one or more material property
12 coefficients;
13 (5) comparing each of the plurality of values in the material property matrix
14 $[k]$ to known material properties and, responsive to a match, selecting a corresponding
15 manufacturing process parameter, wherein the selected manufacturing process parameter
16 is usable for controlling composite manufacturing equipment if the matched known
17 material property is a material property for a composite material; and
18 (6) controlling the composite manufacturing equipment in accordance with
19 the selected manufacturing process parameters to thereby manufacture the object.

1 42. The method according to claim 41, wherein the object being manufactured
2 is a prosthetic implant for replacing a body part and the force $\{f\}$ and displacement $\{x\}$
3 are specified based on the in vivo forces applied to the body part to be replaced and the in
4 vivo displacements generated in the body part to be replaced when the forces are applied
5 thereto.